

Calvin Robinson

Resources

- Raspbian Stretch Lite www.raspberrypi. org/downloads
- Etcher
- N-0-D-E https://github. com/N-O-D-E/ Dongle
- RubberDucky **Payloads** https://github.com hak5darren/USB-Rubber-Ducky/ wiki/Payloads

Turn the Raspberry Pi into a remote hacking device

Using a few scripts, we're going to turn a Zero W into a 'Rubber Ducky' pentesting tool



RubberDucky USB devices are great penetrationtesting tools. This device is plugged into a target computer, and the USB drive tricks the computer into thinking it's a HID keyboard device in order to gain privileged access. Keyboards naturally provide a user with unrestricted access to the computer, in ways that a USB stick wouldn't normally be able to.

Pre-configured 'Ducky' scripts are then run on the target machine to prank the user or provide unauthorised remote access. Not only are we going to turn a Raspberry Pi Zero W into a USB device capable of running Ducky scripts, we're also going to gain remote access to the target machine in order to select which scripts we'd like to run, and gain shell access on the target PC.

For the sake of this tutorial we're assuming the target is running Windows and we - the attacker - are running a variant of Linux, but Rubber Duckys essentially work on any operating system. Scripts are available for Windows, Linux and OS X.



Preparation - the hardware In order to get our Raspberry Pi set up as a USB device we'll need:

- · A long USB cable with power adaptor
- A USB hub (for connecting multiple USB devices at the

- A USB Ethernet adaptor and Ethernet cable (to gain internet access without having to mess around with
- A Mini HDMI to HDMI cable and a monitor to connect vour Pi to
- A standard USB keyboard
- · A microSD card

If you really want your Pi to look like a USB device, take a look at the N-O-D-E case (there's a link in the Resources section). Some soldering may be required. If you're not using the N-O-D-E, you'll need a small USB to Micro-USB cable for connecting the Pi to your target PC.

Preparation - the software

Download the latest version of Raspbian Stretch

Lite, and some software to write the image onto your microSD card - we recommend Etcher for this.

Once you've got Raspbian Stretch Lite installed, plug in a monitor and keyboard and boot your Pi. You can also use ssh for this step, if you can find the IP address of your Pi by checking your router or by using a network sniffer



such as Angry IP Scanner. Once in, the default login details will be username: pi password: raspberry.

Next up we'll need to install git and download a clone of P4wnP1, which is the toolset that turns our Pi into a USB device.

Installation – git-cloning P4wnP1
Just run the following lines one by one:

mkdir ~/P4wnP1 cd ~/P4wnP1

sudo apt-get install git

git clone --recursive https://github.com/

⇔ Settings Device is ready 'P4wnP1 by MaMe82' is set up and ready to Setting up a device We're setting up 'P4wnP1 by MaMe82'.

mame82/P4wnP1 ./install.sh

Grab a cup of tea, as installation may take some time. Once complete, note down the Wi-Fi name, key and SSH access displayed on the screen. We can of course change these later

Test the connectionNow that everything is set up, we should have a basic working P4wnP1 USB device. Before we set up our payload and customise our settings it's good to test that everything is working. We'll need two computers for this,



one to be used as a target and the other for our remote control 'attacker'.

Plug the Pi into a target machine - which must be a working computer that is turned on - using the Pi's middle USB port (the one for data, not power). You should notice a couple of things: the target machine will display discrete pop-ups saying Setting up a device followed by Device is ready. At the moment, this new USB device will be called 'P4wnP1 by MaMe82' but we can change that later. On the attacker's machine we should see a new Wi-Fi network called P4wnP1, which means all is working as intended.

O5 Customise your USB Pi
Now that the Pi is up and running, we'll want to either plug it back into a screen and keyboard, as we did earlier, or connect remotely over SSH at the address we noted down (172.24.0.1). Change directory into ~/P4wnP1 and run nano setup.cfg. Here you'll see a whole range of settings, but ignore these for now as they'll mostly be overwritten by our payload config. What we want to do next is scroll to the end of the document and uncomment our payload of choice. For this tutorial we'll be using hid_backdoor_remote.txt, which enables all the fancy RubberDucky functionality. Be sure to comment out the network_only.txt payload with a #. Save and exit.

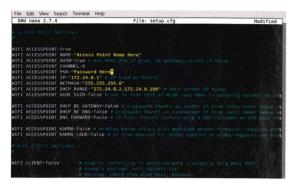
O6 Setup your payload
Change directory to payloads and nano-edit the appropriate config file, in this case hid_backdoor_ remote. Here you may want to change several settings. but most importantly WIFI_ACCESSPOINT_NAME and WIFI_ACCESSPOINT_PSK, which are of course the SSID and

A powerful weapon

Our Rasperry Pi Zero W is now an advanced Rubber Ducky USB device. We can take complete control of a remote machine, be it running Windows, Linux, Mac OS X or even Android. Remember to use this tool responsibly!

password required to remotely connect to your USB Pi. It may also be useful to change the keyboard language setting (lang) from us to gb.

There are some rather interesting settings in this payload, namely the reachback connection or AutoSSH. This will enable the Pi device to automatically connect to a a server of your choosing, via SSH, to essentially provide a backdoor tunnel.



Hack via Wi-Fi

While the AutoSSH functionality is fantastic, particularly for out-of-sight or long-range remote hacking, for the purposes of this tutorial we're going to stick with line-of-sight and/or short-range remote hacking via a local Wi-Fi connection.

Pop the Pi into a target machine and connect remotely via SSH to pi@172.24.0.1. A more discrete way of doing this, rather than using a laptop for attacking, could be to use an Android mobile phone with a Terminal/ SSH client installed. Once connected, type help for a list of commands. If you didn't change the keyboard

Right The FireStage1 script running in PowerShell on target machine



layout in payload settings earlier you'll need to do so now, before passing any commands over to the target. GetKeyboardLayout shows the current setting and SetKeyboardLayout gives a list of options.

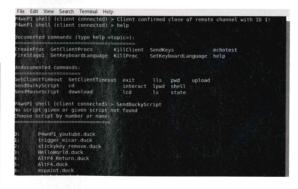
By default P4wnP1 shell will say client not connected. To gain remote access to the target machine we'll need to initiate the FireStage1 command. This will briefly open a PowerShell window on the target, before taking advantage of a few exploits and disappearing again. We now have pretty much full control over the



target machine - whatever the end user has access to,

Typing shell will give an MS-DOS-style command prompt, where you'll be able to use cmd as a regular user. Type running some basic Windows commands such as dir to see what happens. Type exit to guit the shell.

Playing with RubberDucky payloads
Having shell access is great, but we're really here for the RubberDucky scripts. To run one of these payloads simply type SendDuckyScript and you'll be greeted with a list of all the scripts currently stored on the microSD. By default there are seven scripts to play with, but there are also hundreds of other pre-configured



scripts available online. We've linked to Daren Kitchen/ Hak5's payloads in the Resources tab, where you'll find dozens of high-quality payloads.

P4wnP1-youtube.duck launches a YouTube video on the target machine, Trigger_eicar.duck checks for an installed antivirus. AltF4_Return.duck, AltF4. duck, Stickykey.duck and Stickykey_remove.duck are quite self-explanatory, while HelloWorld.duck opens a NotePad and types the message Hello World.

10 Edit RubberDucky payloads
We can open .duck files in a text editor such as nano and make our own customisations. HelloWorld. duck is a great place to start – try fiddling about with it. By default it looks like this:

GUI r DELAY 500 STRING notepad.exe **ENTER** DELAY 1000 STRING Hello World

Configure RubberDucky payloads The delays are there to give the computer a chance to load software. GUI r opens Windows' Run dialogue window; our script then waits a few milliseconds before typing the string of text notepad.exe and pressing the Enter (Return) key. After another short delay (for Notepad to load) our script types out another string. We could of course edit this string or add multiple strings below it, to display our own custom messages on the target's screen:

■ STRING Please remember to lock your PC and protect your USB ports.

12 Add more RubberDucky payloads
By creating .duck text files in /P4wnP1/ DuckyScripts we can collate as many RubberDucky scripts as we like, and they'll all be listed by the SendDuckyScript comment on our USB Pi.

■ GUI r DELAY 500 STRING iexplore -k http://fakeupdate.net/ win10u/index.html ENTER

This script loads a full-screen 'Windows Update' screen as a prank.

How to use hidden commands
There a few handy commands not listed under the

help command, such as these:

KillProc Try to kill the given remote process KillClient Try to kill the remote client CreateProc This remote PowerShell method calls core_create_proc in order to create a remote process GetClientProcs Print a list of processes managed by the remote client

Interact Interact with processes on the target. Usage: Interact process ID>

SendKeys Print out everything on target through the HID keyboard

exit Exit the Backdoor payload and return to the Pi's command line

state See details about the target computer echotest If the client is connected, command arguments given should be reflected back

Pi commands

P4wnP1 also allows for the use of some Linux commands, regardless of the target operating system: · lcd Change directory on the Pi

Left Rubber Ducky device connected and no USB devices showing in My Computer in Windows

1pwd Print the name of the Pi's current directory 11s Print the contents of the Pi's current directory pwd Print the target's current directory 1s List contents of the target's current directory cd Change the target's current directory upload Upload a file from the Pi to the target. Usage: upload <Pi/directory.filetype> <target/directory. filetype>

download Download a file from the Pi to the target. Usage: download <target/directory.filetype> <Pi/directory.filetype>

run_method This is undocumented for now

15 Obtaining user credentials
Of course we've only used the network_only. txt and hid_backdoor_remote.txt P4wnP1 payloads in this tutorial, but others are available. Try switching to the hakin9_tutorial/payload.txt instead, as this takes things a step further.

Instead of only replicating a HID keyboard interface, hakin9 also replicates a RNDIS network device and a USB mass-storage device. Therefore we can run a script that steals a user's credentials via PowerShell and then saves them directly to the USB. This would mean you could plug in the USB device, run the script, pull it out and walk away. The target would be none the wiser.

16 Other payloads
Once you're comfortable with hid_backdoor_ remote and hakin9 there are a number of other payloads to play around with in P4wnP1. Win10_LockPicker attempts to grab Windows 10 login details, hid_mouse sets up the Pi to emulate mouse functionality instead of a keyboard, offering a completely different toolset, and wifi_connect is the infamous AuthSSH attack

■ Where'd it go?

Enter to bypass any 'Save' dialogue that may pop up to prever

DELAY 500